CONDITIONING OF THE STABLE, DISCRETE-TIME LYAPUNOV OPERATOR*

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Abstract. The Schatten *p*-norm condition of the discrete-time Lyapunov operator \mathcal{L}_A defined on matrices $P \in \mathbb{R}^{n \times n}$ by $\mathcal{L}_A P \equiv P - APA^T$ is studied for stable matrices $A \in \mathbb{R}^{n \times n}$. Bounds are obtained for the norm of \mathcal{L}_A and its inverse that depend on the spectrum, singular values, and radius of stability of A. Since the solution P of the discrete-time algebraic Lyapunov equation (DALE) $\mathcal{L}_A P = Q$ can be ill-conditioned only when either \mathcal{L}_A or Q is ill-conditioned, these bounds are useful in determining whether P admits a low-rank approximation, which is important in the numerical solution of the DALE for large n.

Key words. Lyapunov matrix equation, condition estimates, large-scale systems, radius of stability

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1. Introduction. Properties of the solution P of the discrete algebraic Lyapunov equation (DALE), $P = APA^T + Q$, are closely related to the stability properties of A. For instance, the DALE has a unique solution $P = P^T > 0$ for any $Q = Q^T > 0$ if A is stable [11], a fact also true in infinite-dimensional Hilbert spaces [18]. In the setting treated here with A, Q, $P \in \mathbb{R}^{n \times n}$, A is stable if its eigenvalues $\lambda_i(A)$, $i = 1, \ldots, n$, lie inside the unit circle; the eigenvalues are ordered so that $|\lambda_1(A)| \geq |\lambda_2(A)| \geq \cdots \geq |\lambda_n(A)|$. Here A is always assumed to be stable.

In applications where the dimension n is very large, direct solution of the DALE or even storage of P is impractical or impossible. For instance, in numerical weather prediction applications A is the matrix that evolves atmospheric state perturbations. The DALE and its continuous-time analogues can be solved directly for simplified atmospheric models [6, 23], but in realistic models n is about $10^6 - 10^7$ and even the storage of P is impossible. Krylov subspace [5] and Monte Carlo [9] methods have been used to find low-rank approximations of the right-hand side of the DALE and of the solution of the DALE [10].

The solution P of the DALE can be well approximated by a rank-deficient matrix if P has some small singular values. Therefore, it is useful to identify properties of A

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or Q that lead to P being ill-conditioned. If A is normal, then

(1.1)
$$\frac{\lambda_1(P)}{\lambda_n(P)} \le \frac{\lambda_1(Q)}{\lambda_n(Q)} \frac{1 - |\lambda_n(A)|^2}{1 - |\lambda_1(A)|^2};$$

the conditioning of P is controlled by that of Q and by the spectrum of A. In the general case, the conditioning of Q and of the discrete-time Lyapunov operator \mathcal{L}_A defined by $\mathcal{L}_A P \equiv P - APA^T$ determine when P may be ill-conditioned.

THEOREM 1.1. Let A be a stable matrix and suppose that $\mathcal{L}_A P = Q$ for $Q = Q^T > 0$. Then

(1.2)
$$\|P\|_p \|P^{-1}\|_p \leq \|\mathcal{L}_A\|_p \|\mathcal{L}_A^{-1}\|_p \|Q\|_p \|Q^{-1}\|_p, \qquad p = \infty,$$

where $\|\cdot\|_p$ is the Schatten p-norm (see (2.2)).

Theorem 1.1 (see proof in the appendix) follows from \mathcal{L}_A^{-1} and its adjoint being positive operators. Therefore, the same connection between rank-deficient approximate solutions and operator conditioning exists for matrix equations such as the continuous algebraic Lyapunov equation. We note that Theorem 1.1 also holds for $1 \leq p < \infty$ if either A is singular or $\sigma_1^2(A) \geq 2$; $\sigma_1(A)$ is the largest singular value of A.

Here we characterize the Schatten *p*-norm condition of \mathcal{L}_A . The main results are the following. Theorem 3.1 bounds $\|\mathcal{L}_A\|_p$ in terms of the singular values of A. A lower bound for $\|\mathcal{L}_A^{-1}\|_p$ depending on $\lambda_1(A)$ is presented in Theorem 4.1, generalizing results of [7]. Theorem 4.2 gives lower bounds for $\|\mathcal{L}_A^{-1}\|_1$ and $\|\mathcal{L}_A^{-1}\|_\infty$ in terms of the singular values of A. Theorem 4.6 gives an upper bound for $\|\mathcal{L}_A^{-1}\|_p$ depending on the radius of stability of A and generalizes results in [20]. Three examples illustrating the results are included. The issue of whether \mathcal{L}_A and \mathcal{L}_A^{-1} achieve their norms on symmetric, positive definite matrices is addressed in the concluding remarks.

2. Preliminaries. We investigate the condition number $\kappa(\mathcal{L}_A) = \|\mathcal{L}_A\| \|\mathcal{L}_A^{-1}\|$, where $\|\cdot\|$ is a norm on $\mathbb{R}^{n^2 \times n^2}$ induced by a matrix norm on $\mathbb{R}^{n \times n}$. Specifically, for $\mathcal{M} \in \mathbb{R}^{n^2 \times n^2}$ we consider norms defined by

(2.1)
$$\|\mathcal{M}\|_p = \max_{S \neq 0 \in \mathbb{R}^{n \times n}} \frac{\|\mathcal{M}S\|_p}{\|S\|_p}, \quad 1 \le p \le \infty,$$

where the Schatten matrix *p*-norm for $S \in \mathbb{R}^{n \times n}$ is defined by

(2.2)
$$||S||_p = \left(\sum_{i=1}^n \left(\sigma_i(S)\right)^p\right)^{1/p};$$

 $\sigma_i(S)$ are the singular values of S with ordering $\sigma_1(S) \geq \sigma_2(S) \geq \cdots \geq \sigma_n(S) \geq 0$. On $\mathbb{R}^{n \times n}$, $\|\cdot\|_2$ is the Frobenius norm and $\|\cdot\|_{\infty} = \sigma_1(\cdot)$. If $S = S^T \geq 0$, then $\|S\|_1 = \operatorname{tr} S$. The following lemma about the Schatten *p*-norms follows from their being unitarily invariant [1, p. 94].

LEMMA 2.1. For any three matrices X, Y, and $Z \in \mathbb{R}^{n \times n}$,

(2.3)
$$||XYZ||_p \le ||X||_{\infty} ||Y||_p ||Z||_{\infty}, \quad 1 \le p \le \infty$$

The p = 2 Schatten norm on $\mathbb{R}^{n \times n}$ is equivalently defined as $||S||_2^2 = (S, S)$, where (\cdot, \cdot) is the inner product on $\mathbb{R}^{n \times n}$ defined by $(S_1, S_2) = \operatorname{tr} S_1^T S_2$. This norm corresponds to the usual Euclidean norm on \mathbb{R}^{n^2} since $||S||_2^2$ is equal to the sum of the squares of the entries of S. As a consequence $\kappa_2(\mathcal{L}_A) = \sigma_1(\mathcal{L}_A)/\sigma_{n^2}(\mathcal{L}_A)$, where $\sigma_1(\mathcal{L}_A)$ and $\sigma_{n^2}(\mathcal{L}_A)$ are, respectively, the largest and smallest singular values of \mathcal{L}_A . The adjoint of \mathcal{L}_A is given by $\mathcal{L}_A^*S = \mathcal{L}_{A^T}S = S - A^TSA$.

We now state some lemmas about mappings $\mathcal{M} \in \mathbb{R}^{n^2 \times n^2}$ and about the spectra of \mathcal{L}_A and A.

LEMMA 2.2 (see [2, equation (15)]). $\|\mathcal{M}\|_p \leq \|\mathcal{M}\|_1^{1/p} \|\mathcal{M}\|_{\infty}^{1-1/p}$, $1 \leq p \leq \infty$. LEMMA 2.3. $\|\mathcal{M}\|_1 = \|\mathcal{M}^*\|_{\infty}$.

LEMMA 2.4 (see [2, proof of Theorem 1]). If $\mathcal{M}S > 0$ for all $S \in \mathbb{R}^{n \times n}$ such that S > 0, then $\|\mathcal{M}\|_{\infty} = \|\mathcal{M}I\|_{\infty}$.

LEMMA 2.5 (see [13, 14]). The n^2 eigenvalues of \mathcal{L}_A are $1 - \lambda_i(A)\overline{\lambda_j(A)}, 1 \leq i, j \leq n$.

3. The norm of the Lyapunov operator. If A is normal, then \mathcal{L}_A is normal, and its conditioning in the p = 2 Schatten norm depends only on its eigenvalues. Therefore, when A is normal,

(3.1)
$$\|\mathcal{L}_{A}^{-1}\|_{2} = \frac{1}{\sigma_{n^{2}}(\mathcal{L}_{A})} = \frac{1}{|\lambda_{n^{2}}(\mathcal{L}_{A})|} = \frac{1}{1 - |\lambda_{1}(A)|^{2}}$$

and

(3.2)
$$\|\mathcal{L}_A\|_2 = \sigma_1(\mathcal{L}_A) = |\lambda_1(\mathcal{L}_A)| = \max_{i,j} |1 - \lambda_i(A)\overline{\lambda_j(A)}|.$$

For general A, the following theorem bounds $\|\mathcal{L}_A\|_p$ in terms of the singular values of A.

Theorem 3.1.

(3.3)
$$|1 - \sigma_1^2(A)| \le \max_j |1 - \sigma_j^2(A)| \le \|\mathcal{L}_A\|_p \le 1 + \sigma_1^2(A), \quad 1 \le p \le \infty.$$

Proof. Note that $\mathcal{L}_A v_j v_j^T = v_j v_j^T - \sigma_j^2 u_j u_j^T$, where u_j and v_j are, respectively, the *j*th left and right singular vectors of A such that $Av_j = \sigma_j u_j$. The lower bound follows from $\|u_j u_j^T\|_p = \|v_j v_j^T\|_p = 1$ and

(3.4)
$$\|\mathcal{L}_A\|_p \ge \|v_j v_j^T - \sigma_j^2 u_j u_j^T\|_p \ge \left|\|v_j v_j^T\|_p - \|\sigma_j^2 u_j u_j^T\|_p\right| = \left|1 - \sigma_j^2\right|.$$

The upper bound follows from

(3.5)
$$\|\mathcal{L}_A P\|_p \le \|P\|_p + \|APA^T\|_p \le \|P\|_p + \|A\|_{\infty}^2 \|P\|_p .$$

If A is normal, $\sigma_j(A)$ can be replaced by $|\lambda_j(A)|$ in Theorem 3.1, and $\|\mathcal{L}_A\|_p \leq 1 + |\lambda_1(A)|^2$. If A is normal and $(-\overline{\lambda_1(A)})$ is an eigenvalue of A, then $1 + |\lambda_1(A)|^2$ is an eigenvalue of \mathcal{L}_A and $\|\mathcal{L}_A\|_p = 1 + |\lambda_1(A)|^2$.

Theorem 3.1 shows that $\|\mathcal{L}_A\|_p$ is large and contributes to ill-conditioning if and only if $\sigma_1(A)$ is large, a situation that occurs in various applications [3, 22]. If $\sigma_1(A) \gg 1$ and $|\lambda_1(A)| < 1$, A is highly nonnormal [8, p. 314] and, as Corollary 4.8 will show, close to an unstable matrix.

4. The norm of the inverse Lyapunov operator. We first show that a sufficient condition for $\|\mathcal{L}_A^{-1}\|_p$ to be large is that $\lambda_1(A)$ be near the unit circle. The condition is necessary when A is normal.

THEOREM 4.1. Let A be a stable matrix. Then

(4.1)
$$\|\mathcal{L}_{A}^{-1}\|_{p} \ge \frac{1}{1-|\lambda_{1}(A)|^{2}}, \quad 1 \le p \le \infty,$$

with equality holding if A is normal.

Proof. To obtain the lower bound, let z_1 be the leading eigenvector of A, $Az_1 = \lambda_1(A)z_1$, and note that $\mathcal{L}_A z_1 z_1^H = (1 - |\lambda_1(A)|^2)z_1 z_1^H$, where $(\cdot)^H$ denotes conjugate transpose. Either $\operatorname{Re} z_1 z_1^H \neq 0$ or $\operatorname{Im} z_1 z_1^H \neq 0$ is an eigenvector of \mathcal{L}_A , and it follows that $\|\mathcal{L}_A^{-1}\|_p \geq (1 - |\lambda_1(A)|^2)^{-1}$. Finally, if A is normal, then

(4.2)
$$\mathcal{L}_{A^T}^{-1}I = \mathcal{L}_A^{-1}I = \sum_{i=1}^n \frac{1}{1 - |\lambda_i(A)|^2} z_i z_i^H,$$

and $\|\mathcal{L}_A^{-1}\|_{\infty} = \|\mathcal{L}_A^{-1}\|_1 = (1 - |\lambda_1(A)|^2)^{-1}$. Using Lemma 2.2 gives $\|\mathcal{L}_A^{-1}\|_p \leq (1 - |\lambda_1(A)|^2)^{-1}$ when A is normal, and therefore $\|\mathcal{L}_A^{-1}\|_p = (1 - |\lambda_1(A)|^2)^{-1}$. When A is nonnormal, $\|\mathcal{L}_A^{-1}\|_p$ can be large without $\lambda_1(A)$ being near the unit

When A is nonnormal, $\|\mathcal{L}_A^-\|_p$ can be large without $\lambda_1(A)$ being near the unit circle. For instance, if $\sigma_1(A)$ is large or, more generally, if $\|A^k\|_{\infty}$ converges to zero slowly as a function of k, then $\|\mathcal{L}_A^{-1}\|_p$ is large. We show this fact first for $p = 1, \infty$. THEOREM 4.2. Let A be a stable matrix. For all $m \geq 1$,

$$(43) \qquad \|\mathcal{L}^{-1}\|_{\star} = \left\|\sum_{k=1}^{\infty} (A^{k})^{\mathrm{T}} A^{k}\right\| \qquad > \left\|\sum_{k=1}^{m} (A^{k})^{\mathrm{T}} A^{k}\right\| + \frac{\sigma_{n}^{2(m+1)}(A)}{\sigma_{n}^{2(m+1)}(A)}$$

(4.3)
$$\|\mathcal{L}_{A}^{-1}\|_{1} = \left\|\sum_{k=0}^{\infty} (A^{k})^{\mathrm{T}} A^{k}\right\|_{\infty} \ge \left\|\sum_{k=0}^{\infty} (A^{k})^{\mathrm{T}} A^{k}\right\|_{\infty} + \frac{\sigma_{n}^{n}}{1 - \sigma_{n}^{2}(A)},$$

(4.4) $\|\mathcal{L}_{A}^{-1}\|_{\infty} = \left\|\sum_{k=0}^{\infty} A^{k} (A^{k})^{\mathrm{T}}\right\|_{\infty} \ge \left\|\sum_{k=0}^{m} A^{k} (A^{k})^{\mathrm{T}}\right\|_{\infty} + \frac{\sigma_{n}^{2(m+1)}(A)}{1 - \sigma_{n}^{2}(A)},$

(4.4)
$$\|\mathcal{L}_{A}^{-1}\|_{\infty} = \left\|\sum_{k=0}^{\infty} A^{k} (A^{k})^{T}\right\|_{\infty} \ge \left\|\sum_{k=0}^{\infty} A^{k} (A^{k})^{T}\right\|_{\infty} + \frac{\sigma n}{1 - \sigma_{n}^{2}(A)}$$

In particular,

(4.5)
$$\|\mathcal{L}_A^{-1}\|_p \ge 1 + \sigma_1^2(A) + \frac{\sigma_n^4(A)}{1 - \sigma_n^2(A)}, \qquad p = 1, \infty$$

Proof. The operator \mathcal{L}_A^{-1} applied to $S \in \mathbb{R}^{n \times n}$ can be expressed as [18]

(4.6)
$$\mathcal{L}_{A}^{-1}S = \sum_{k=0}^{\infty} A^{k}S \left(A^{k}\right)^{\mathrm{T}}.$$

Applying Lemma 2.4 gives $\|\mathcal{L}_A^{-1}\|_{\infty} = \|\mathcal{L}_A^{-1}I\|_{\infty}$, with the inequality in (4.4) being a consequence of

(4.7)
$$\left\|\sum_{k=0}^{\infty} A^{k} \left(A^{k}\right)^{\mathrm{T}}\right\|_{\infty} \geq \left\|\sum_{k=0}^{m} A^{k} \left(A^{k}\right)^{\mathrm{T}}\right\|_{\infty} + \lambda_{n} \left(\sum_{k=m+1}^{\infty} A^{k} \left(A^{T}\right)^{k}\right),$$

and

(4.8)

$$\lambda_n \left(\sum_{k=m+1}^{\infty} A^k (A^T)^k \right) \ge \sum_{k=m+1}^{\infty} \lambda_n \left(A^k (A^T)^k \right) \ge \sum_{k=m+1}^{\infty} \sigma_n^{2k} (A) = \frac{\sigma_n^{2(m+1)}(A)}{1 - \sigma_n^2(A)},$$

where we have used the facts that for matrices $W, X, Y \in \mathbb{R}^{n \times n}$ with X, Y being symmetric positive semidefinite, $\lambda_i(X+Y) \geq \lambda_i(X) + \lambda_n(Y)$, and $\lambda_i(WXW^T) \geq \sigma_n^2(W)\lambda_i(X)$ [17]. Likewise the p = 1 results follow from $\|\mathcal{L}_A^{-1}\|_1 = \|\mathcal{L}_A^{-1}I\|_{\infty}$. Lower bounds for 1 follow trivially, e.g.,

(4.9)
$$\|\mathcal{L}_{A}^{-1}\|_{p} \geq \frac{\|\mathcal{L}_{A}^{-1}I\|_{p}}{\|I\|_{p}} = \frac{\|\mathcal{L}_{A}^{-1}I\|_{p}}{n^{1/p}} \geq n^{-1/p}\|\mathcal{L}_{A}^{-1}\|_{\infty}$$

but give little information when n is large. A lower bound for $1 \le p \le \infty$ depending on $\sigma_1(A)$ and independent of n is given in Corollary 4.9.

We now relate $\|\mathcal{L}_A^{-1}\|_p$ to the distance from A to the set of unstable matrices as measured by its *radius of stability* [15].

DEFINITION 4.3. For any stable matrix $A \in \mathbb{R}^{n \times n}$ define the radius of stability r(A) by

(4.10)
$$r(A) \equiv \min_{0 \le \theta \le 2\pi} \| (e^{i\theta}I - A)^{-1} \|_{\infty}^{-1} = \min_{0 \le \theta \le 2\pi} \| R(e^{i\theta}, A) \|_{\infty}^{-1},$$

where the resolvent of A is $R(\lambda, A) = (\lambda I - A)^{-1}$.

If A is normal and stable, then $r(A) = 1 - |\lambda_1(A)|$. However, if A is nonnormal and if its eigenvalues are *sensitive* to perturbations, then $r(A) \ll 1 - |\lambda_1(A)|$. The sensitivity of the eigenvalues of A is most completely described by its *pseudospectrum* [21]. The radius of stability r(A) is the largest value of ϵ such that the ϵ -pseudospectrum of A lies inside the unit circle; r(A) being small indicates that the ϵ -pseudospectrum of A is close to the unit circle for small ϵ . The following theorem shows that when r(A) is small, $\|\mathcal{L}_A^{-1}\|_p$ must be large.

THEOREM 4.4 (proven for $p = \infty$ in [7]). Let A be a stable matrix. Then

(4.11)
$$\|\mathcal{L}_A^{-1}\|_p \ge \frac{1}{2r(A) + r^2(A)}, \quad 1 \le p \le \infty.$$

Proof. There exists a matrix $E \in \mathbb{R}^{n \times n}$ with $|\lambda_1(A + E)| = 1$ and $||E||_{\infty} = r(A)$. Therefore, there exists a vector x with $x^H x = 1$ such that $(A + E)x = e^{i\theta}x$ for some $0 \le \theta \le 2\pi$. Using $||xx^H||_p = 1$ and Lemma 2.1 gives

(4.12)
$$\begin{aligned} \|\mathcal{L}_A x x^H\|_p &= \| - E x x^H E^T + e^{i\theta} x x^H E^T + e^{-i\theta} E x x^H \|\\ &\leq \|E x x^H E^T\|_p + \|x x^H E^T\|_p + \|E x x^H\|_p \\ &\leq \|E\|_{\infty}^2 + 2\|E\|_{\infty} = r^2(A) + 2r(A) \,, \end{aligned}$$

and we have

(4.13)
$$\|\mathcal{L}_{A}^{-1}\|_{p} \geq \frac{\|\mathcal{L}_{A}^{-1}\mathcal{L}_{A}xx^{H}\|_{p}}{\|\mathcal{L}_{A}xx^{H}\|_{p}} = \frac{1}{\|\mathcal{L}_{A}xx^{H}\|_{p}} \geq \frac{1}{2r(A) + r^{2}(A)} .$$

A consequence of Theorem 4.4 is the following lower bound for r(A) in terms of $\|\mathcal{L}_A^{-1}\|_p$.

COROLLARY 4.5. Let A be a stable matrix. Then

(4.14)
$$r(A) \ge \frac{\|\mathcal{L}_A^{-1}\|_p^{-1}}{1 + \sqrt{1 + \|\mathcal{L}_A^{-1}\|_p^{-1}}}, \qquad 1 \le p \le \infty.$$

Bounds for r(A) are useful in robust stability [12] and in the study of perturbations of the discrete algebraic Riccati equation (DARE) [19]. In [19, Lemma 2.2] the bound

(4.15)
$$r(A) \ge \frac{\|\mathcal{L}_A^{-1}\|_{\infty}^{-1}}{\sigma_1(A) + \sqrt{\sigma_1^2(A) + \|\mathcal{L}_A^{-1}\|_{\infty}^{-1}}}$$

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was used to formulate conditions under which a perturbed DARE has a unique, symmetric, positive definite solution. Since the lower bound in (4.14) with $p = \infty$ is sharper than that in (4.15) when $\sigma_1(A) > 1$, it can be used to show existence of a unique, symmetric, positive definite solution of the perturbed DARE for a larger class of perturbations [19, Theorem 4.1].

We generalize to Schatten p-norms the conjecture of [7] proven in [20] for the Frobenius norm.

THEOREM 4.6. Let A be a stable matrix. Then

(4.16)
$$\|\mathcal{L}_{A}^{-1}\|_{p} \leq \frac{1}{r^{2}(A)}, \quad 1 \leq p \leq \infty.$$

Proof. $\mathcal{L}_A^{-1}I$ can be expressed as [20, 13]

(4.17)
$$\mathcal{L}_{A}^{-1}I = \frac{1}{2\pi} \int_{0}^{2\pi} R(e^{i\theta}, A) R(e^{i\theta}, A)^{H} d\theta.$$

Therefore, from Lemma 2.4,

(4.18)
$$\|\mathcal{L}_{A}^{-1}\|_{\infty} = \|\mathcal{L}_{A}^{-1}I\|_{\infty} \le \frac{1}{2\pi} \int_{0}^{2\pi} \|R(e^{i\theta}, A)\|_{\infty}^{2} d\theta \le \frac{1}{r^{2}(A)} \, .$$

The inequality (4.16) for p = 1 follows from $\|\mathcal{L}_A^{-1}\|_1 = \|\mathcal{L}_A^{-1}I\|_\infty$ and $r(A) = r(A^T)$. The theorem follows from Lemma 2.2. \Box

As a consequence, any solution of the DALE can be used to obtain an upper bound for r(A).

COROLLARY 4.7. Let A be a stable matrix and let $\mathcal{L}_A P = Q$. Then

(4.19)
$$r^2(A) \le \frac{\|Q\|_p}{\|P\|_p}, \qquad 1 \le p \le \infty$$

Theorem 4.6 can be combined with any lower bound for $\|\mathcal{L}_A^{-1}\|_p$ to obtain an upper bound for r(A). For instance, from Theorem 4.2 we get the following upper bound.

COROLLARY 4.8. Let A be a stable matrix. Then

(4.20)
$$r^2(A) \le \frac{1}{1 + \sigma_1^2(A)}.$$

Combining Corollary 4.8 and Theorem 4.4 gives a lower bound for $\|\mathcal{L}_A^{-1}\|_p$. COROLLARY 4.9. Let A be a stable matrix. Then

(4.21)
$$\|\mathcal{L}_A^{-1}\|_p \ge \frac{1 + \sigma_1^2(A)}{1 + 2\sqrt{1 + \sigma_1^2(A)}}, \qquad 1 \le p \le \infty$$

5. Examples. We present three examples that illustrate how ill-conditioning of \mathcal{L}_A leads to low-rank approximate solutions of the DALE.

Example 1. Almost unit eigenvalues. Take $A = \lambda z z^T$, where λ and z are real, $0 < \lambda < 1$, and $z^T z = 1$. The matrix A is symmetric and \mathcal{L}_A is self-adjoint. The eigenvalues of A are $(\lambda, 0, \ldots, 0)$. The operator \mathcal{L}_A has singular values (and eigenvalues) $(1, \ldots, 1, 1 - \lambda^2)$. Therefore, $\|\mathcal{L}_A\|_2 = 1$ and $1 \leq \|\mathcal{L}_A\|_p \leq 1 + \lambda^2$ from Theorem 3.1. The norm of the inverse Lyapunov operator is

(5.1)
$$\|\mathcal{L}_{A}^{-1}\|_{p} = \frac{1}{1-\lambda^{2}}, \qquad 1 \le p \le \infty,$$

according to Theorem 4.1. As the eigenvalue λ approaches the unit circle, \mathcal{L}_A is increasingly poorly conditioned. The solution of the DALE for this choice of A is

(5.2)
$$P = \frac{\lambda^2}{1 - \lambda^2} \left(z^T Q z \right) z z^T + Q z$$

A "natural" rank-1 approximation \tilde{P} of P is $\tilde{P} = \lambda^2 (1 - \lambda^2)^{-1} (z^T Q z) z z^T$. As the eigenvalue λ approaches the unit circle, if $(z^T Q z)$ is nonzero, P is increasingly well approximated by \tilde{P} in the sense that $\|P - \tilde{P}\|_p / \|P\|_p$ approaches zero. Example 2. Large singular values. Take $A = \sigma y z^T$, where $\sigma > 0$ and y and z

Example 2. Large singular values. Take $A = \sigma y z^T$, where $\sigma > 0$ and y and z are real unit *n*-vectors. The matrix A has at most one nonzero eigenvalue, namely, $\lambda = \sigma(y^T z)$, taken to be less than one in absolute value. The sensitivity s of the eigenvalue λ is the cosine of the angle between y and z, i.e., $s = \lambda/\sigma$ for $\lambda \neq 0$, indicating that λ is sensitive to perturbations to A when σ is large [8].

Theorem 3.1 gives that $1 + \sigma^2 \ge \|\mathcal{L}_A\|_p \ge |1 - \sigma^2|$, showing that $\|\mathcal{L}_A\|_p$ is large when σ is large. From Lemmas 2.3 and 2.4,

(5.3)
$$\|\mathcal{L}_A^{-1}\|_1 = \|\mathcal{L}_A^{-1}\|_\infty = 1 + \frac{\sigma^2}{1 - \lambda^2},$$

and it follows from Lemma 2.2 that $\|\mathcal{L}_A^{-1}\|_p \leq 1 + \sigma^2/(1-\lambda^2)$. A lower bound for the (p=2)-norm is

(5.4)
$$\|\mathcal{L}_{A}^{-1}\|_{2} \geq \|\mathcal{L}_{A}^{-1}zz^{T}\|_{2} = \sqrt{1 + 2\frac{\lambda^{2}}{1 - \lambda^{2}} + \frac{\sigma^{4}}{(1 - \lambda^{2})^{2}}}.$$

The matrix A is near an unstable matrix either when $|\lambda|$ is near unity or when σ is large since

(5.5)

$$\left\| \left(e^{i\theta}I - \sigma y z^T \right)^{-1} \right\|_{\infty} = \left\| e^{-i\theta}I + \frac{\sigma e^{-2i\theta}}{1 - \lambda e^{-i\theta}} y z^T \right\|_{\infty} \ge 1 + \frac{2|\lambda|}{1 - |\lambda|} + \frac{\sigma^2}{(1 - |\lambda|)^2}.$$

Therefore, $r(A) \leq (1 - |\lambda|)/\sigma$ and a lower bound on $\|\mathcal{L}_A^{-1}\|_p$ follows from Theorem 4.4. When either $|\lambda|$ is close to unity or σ is large, r(A) is small and $\kappa_p(\mathcal{L}_A)$ is large.

The solution of the DALE is

(5.6)
$$P = \frac{\sigma^2}{1 - \lambda^2} \left(z^T Q z \right) y y^T + Q.$$

When \mathcal{L}_A is ill-conditioned and $(z^T Q z) \neq 0$, the rank-1 matrix $\tilde{P} = \sigma^2 (1 - \lambda^2)^{-1} \times (z^T Q z) y y^T$ is a good approximation of P in the sense that $\|P - \tilde{P}\|_p / \|P\|_p$ is small.

Example 3. Sensitive eigenvalues. Consider the dynamics arising from the onedimensional advection equation, $w_t + w_x = 0$ for $0 \le x \le n$, with boundary condition w(0,t) = 0. The matrix A that advances the n-vector $w(x = 1, 2, ..., n, t = t_0)$ to $w(x = 1, 2, ..., n, t = t_0 + 1)$ is the $n \times n$ matrix with ones on the subdiagonal and zero elsewhere, i.e., the transpose of an $n \times n$ Jordan block with zero eigenvalue. Adding stochastic forcing with covariance Q at unit time intervals leads to the DALE, $\mathcal{L}_A P = Q$, where P is the steady-state covariance of w.

Since $\sigma_1(A) = 1$, Theorem 3.1 yields $1 \leq \|\mathcal{L}_A\|_p \leq 2$. Further, since $\|\mathcal{L}_A\|_1 \geq \|\mathcal{L}_A e_1 e_1^T\|_1 = \|e_1 e_1^T - e_2 e_2^T\|_1 = 2$, where e_j is the *j*th column of the identity matrix,

 $\|\mathcal{L}_A\|_1 = 2$. A similar argument with \mathcal{L}_{A^T} gives $\|\mathcal{L}_A\|_{\infty} = 2$. Calculating $\mathcal{L}_A^{-1}I$ and $\mathcal{L}_{A^T}^{-1}I$ gives $\|\mathcal{L}_A^{-1}\|_{\infty} = \|\mathcal{L}_A^{-1}\|_1 = n$. Therefore, using Lemma 2.2, $\|\mathcal{L}_A^{-1}\|_p \leq n$. Also,

(5.7)
$$\|\mathcal{L}_{A}^{-1}\|_{2} \geq \frac{\|\mathcal{L}_{A}^{-1}e_{1}e_{1}^{T}\|_{2}}{\|e_{1}e_{1}^{T}\|_{2}} = \sqrt{n}.$$

A direct calculation shows that

(5.8)
$$\|(e^{i\theta}I - A)^{-1}\|_2^2 = \left\|\sum_{k=0}^{n-1} A^k e^{-i(k+1)\theta}\right\|_2^2 = \frac{n(n+1)}{2}$$

for any real θ . Since $\sqrt{n} \| (e^{i\theta}I - A)^{-1} \|_{\infty} \ge \| (e^{i\theta}I - A)^{-1} \|_2$, we have $r^2(A) \le 2/(n+1)$. Theorem 4.4 then gives a lower bound for $\| \mathcal{L}_A^{-1} \|_p$, $1 \le p \le \infty$. Thus as *n* becomes large; that is, as the domain becomes large with respect to the advection length scale, \mathcal{L}_A is increasingly ill-conditioned.

The elements P_{ij} of the solution P of the DALE are

(5.9)
$$P_{ij} = e_i^T P e_j = \sum_{k=0}^{n-1} e_i^T A^k Q(A^T)^k e_j = \sum_{k=0}^{\min(i-1,j-1)} Q_{i-k,j-k}.$$

Therefore, if $Q = Q^T > 0$, a "natural" rank-*m* approximation of *P* is the matrix \tilde{P} defined by

(5.10)
$$\tilde{P}_{i,j} = \begin{cases} P_{i,j}, & n-m < i, j \le n, \\ 0 & \text{otherwise.} \end{cases}$$

When Q is diagonal, P is also diagonal and

(5.11)
$$P_{ii} = \sum_{k=1}^{i} Q_{kk} \,.$$

In this case, each $Q_{kk} > 0$ and \tilde{P} is the best rank-*m* approximation of *P* in the sense of minimizing $||P - \tilde{P}||_p$. We note that \tilde{P} is associated with the left-most part of the domain $0 \le x \le n$.

6. Concluding remarks. Results about $\|\mathcal{L}_A^{-1}\|_p$ translate into bounds for solutions of the DALE. For instance, the solution P of the DALE for $Q = Q^T \ge 0$ satisfies

(6.1)
$$\operatorname{tr} P \leq \|\mathcal{L}_A^{-1}\|_1 \operatorname{tr} Q$$

and the upper bound is achieved for $Q = w_1 w_1^T$, where w_1 is the leading eigenvector of $\mathcal{L}_{A^T}^{-1}I$. In the $(p = \infty)$ -norm, \mathcal{L}_A^{-1} achieves its norm on the identity. In the (p = 2)-norm, \mathcal{L}_A^{-1} does not in general achieve its norm on the identity, and the question arises whether it achieves its norm on any symmetric, positive semidefinite matrix. The forward operator \mathcal{L}_A does not in general assume its norm on a symmetric, positive semidefinite matrix. The following theorem states that \mathcal{L}_A^{-1} does achieve its (p = 2)-norm on a symmetric, positive semidefinite matrix.

(p=2)-norm on a symmetric, positive semidefinite matrix. THEOREM 6.1. There exists a matrix $S = S^T \ge 0$ such that $\|\mathcal{L}_A^{-1}S\|_2 / \|S\|_2 = \|\mathcal{L}_A^{-1}\|_2$. *Proof.* Theorem 8 of [4] states that the inverse of the stable, continuous-time Lyapunov operator achieves its (p = 2)-norm on a symmetric matrix. The proof is easily adapted to give that \mathcal{L}_A^{-1} achieves its (p = 2)-norm on a symmetric matrix. We now show that if \mathcal{L}_A^{-1} achieves its (p = 2)-norm on a symmetric matrix, it does so on a symmetric, positive semidefinite matrix. Suppose that $\|\mathcal{L}_A^{-1}S\|_2/\|S\|_2 = \|\mathcal{L}_A^{-1}\|_2$ and S is symmetric with Schur decomposition $S = UDU^T$. Define the symmetric, positive semidefinite matrix $S^+ = U|D|U^T$. Then $\|S\|_2 = \|S^+\|_2$ and $-S^+ \leq S \leq S^+$. The positiveness of the stable, discrete-time inverse Lyapunov operator mapping implies that $-\mathcal{L}_A^{-1}S^+ \leq \mathcal{L}_A^{-1}S \leq \mathcal{L}_A^{-1}S^+$, which implies that $\|\mathcal{L}_A^{-1}S\|_2 \leq \|\mathcal{L}_A^{-1}S^+\|_2$. Therefore,

(6.2)
$$\frac{\|\mathcal{L}_A^{-1}S\|_2}{\|S\|_2} = \frac{\|\mathcal{L}_A^{-1}S\|_2}{\|S^+\|_2} \le \frac{\|\mathcal{L}_A^{-1}S^+\|_2}{\|S^+\|_2}. \quad \Box$$

Additional information about the leading singular vectors of \mathcal{L}_A^{-1} could be useful for determining low-rank approximations of P. The power method can be applied to $\mathcal{L}_{A^T}^{-1}\mathcal{L}_A^{-1}$ to calculate the leading right singular vector and singular value of \mathcal{L}_A^{-1} [7]. However, this approach requires solving two DALEs at each iteration, which may be impractical for large n. If it is practical to store P and to apply \mathcal{L}_A and \mathcal{L}_{A^T} , a Lanczos method could be used to compute the trailing eigenvectors of $\mathcal{L}_A \mathcal{L}_{A^T}$ while avoiding the cost of solving any DALEs.

Appendix. Proof of Theorem 1.1. By definition, $||P||_p \leq ||\mathcal{L}_A^{-1}||_p ||Q||_p$, and it remains to show that $||P^{-1}||_{\infty} \leq ||\mathcal{L}_A||_{\infty} ||Q^{-1}||_{\infty}$. Since $P = P^T > 0$, there is a nonzero $x \in \mathbb{R}^n$ such that

(A.1)

$$||P^{-1}||_{\infty} = \frac{1}{\lambda_n(P)} = \frac{x^T x}{x^T \left(\mathcal{L}_A^{-1}Q\right) x} = \frac{\operatorname{tr} x x^T}{\operatorname{tr} \left(\mathcal{L}_A^{-1}Q\right) x x^T} = \frac{\operatorname{tr} x x^T}{\operatorname{tr} \left(\left(\mathcal{L}_{A^T}\right)^{-1} x x^T\right) Q}.$$

Let $B = \mathcal{L}_{A^T}^{-1}(xx^T)$ and note $B = B^T \ge 0$. Then using Lemma 2.3 and tr $BQ \ge \lambda_n(Q)$ tr B gives

$$\|P^{-1}\|_{\infty} = \frac{\operatorname{tr} \mathcal{L}_{A^{T}} B}{\operatorname{tr} B Q} \le \frac{\operatorname{tr} \mathcal{L}_{A^{T}} B}{\operatorname{tr} B} \frac{1}{\lambda_{n}(Q)} \le \|\mathcal{L}_{A^{T}}\|_{1} \|Q^{-1}\|_{\infty} = \|\mathcal{L}_{A}\|_{\infty} \|Q^{-1}\|_{\infty}.$$

Theorem 1.1 holds for $1 \leq p \leq \infty$ given some restrictions on A. From [16], $\lambda_i(P) \geq \lambda_i(Q) + \sigma_n^2(A)\lambda_n(P)$, and it follows that $||P^{-1}||_p \leq ||Q^{-1}||_p$ for $1 \leq p \leq \infty$. From Theorem 3.1, $||\mathcal{L}_A||_p \geq 1$ if either A is singular or $\sigma_1^2(A) \geq 2$. Therefore, if either A is singular or $\sigma_1^2(A) \geq 2$,

(A.3)
$$||P^{-1}||_p \le ||\mathcal{L}_A||_p ||Q^{-1}||_p, \quad 1 \le p \le \infty.$$

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